

Solution, homogeneous, nonhomogeneous.

coefficients, constants

$$x_1 + 2x_2 + 3x_3 + 4x_4 = 8$$

$(x_1, x_2, \dots, x_n)$  vector of unknowns

$$2x_1 + 5x_2 + 10x_3 + 5x_4 = 8$$

Matrix of coefficients

Vector of "system constants"

$$\begin{bmatrix} 1 & 2 & 3 & 4 \\ 2 & 5 & 10 & 5 \end{bmatrix}$$

$$\begin{bmatrix} 8 \\ 8 \end{bmatrix}$$

Solution  $(24 + 5a - 10b, -8 - 4a + 3b, a, b)$

$\forall a, b \in \mathbb{R}$

Means  $x_1 = 24 \dots$

Real solution:  $(x_1, x_2, x_3, \dots, x_n)$

Complex

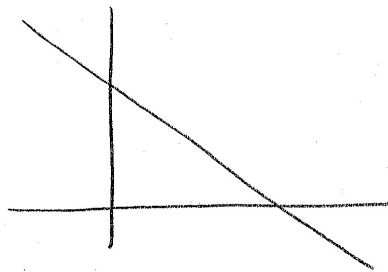
Many ways to write solution:

$$\begin{array}{l|l} x_1 + x_2 = 3 & x_1 = 1 \\ 3x_1 - 2x_2 = -1 & x_2 = 2 \end{array} \quad \text{or } (1, 2)$$

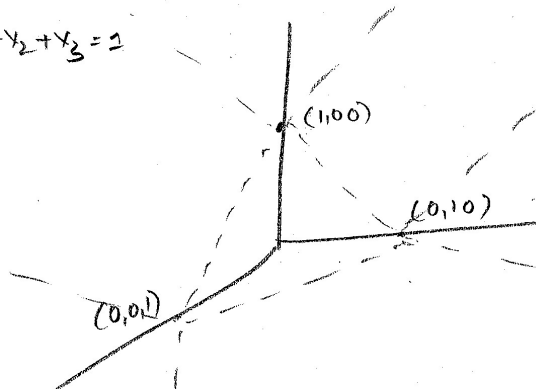
Q: Existence?  
How many?  
How to determine?

Geometry

$$x_1 + x_2 = 3$$



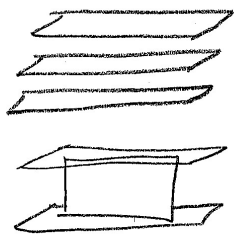
$$x_1 + x_2 + x_3 = 2$$



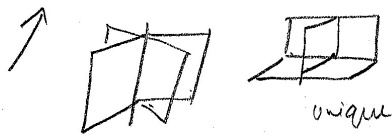
So each equation defines a plane.

3 equations is 3 unknowns.

↓  
defines a plane.



No solutions (No common points in all 3 planes.)



Consistency: at least one solution

Inconsistency: No solution.

Augmented matrix (to be defined next to matrix of coefficients)

Vector formulation

$$-2x_1 + 5x_3 - x_4 = 6$$

$$4x_1 - x_2 + 2x_3 + 2x_4 = -2$$

$$-7x_1 - 6x_2 + 4x_4 = -8$$

$$\begin{bmatrix} -2 & 0 & 5 & -1 \\ 4 & -1 & 2 & 2 \\ -7 & -6 & 0 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 6 \\ -2 \\ -8 \end{bmatrix}$$

We also define the augmented matrix

$$\left[ \begin{array}{cccc|c} -2 & 0 & 5 & -1 & 6 \\ 4 & -1 & 2 & 2 & -2 \\ -7 & -6 & 0 & 4 & -8 \end{array} \right]$$

In general

$$A \vec{x} = \vec{b} \quad \text{is a vector eqn.}$$

$A$  is  $m \times n$      $\vec{x}$  is an  $n \times 1$  column vector

$\vec{b}$  is an  $m \times 1$  column vector.

$\vec{b}$  we may call the "right hand side."

Tuples: set of all <sup>real</sup>  $n$ -tuples  $(c_1, \dots, c_n) = \mathbb{R}^n$   
 " " "complex" " " " " " " =  $\mathbb{C}^n$

Tuples  $\equiv$  (column vectors)<sup>T</sup>  $\equiv$  row vectors

$$(c_1, c_2, \dots) \equiv \begin{bmatrix} c_1 \\ c_2 \\ \vdots \end{bmatrix}^T \equiv [c_1, c_2, \dots]$$

So set of solutions  $S$  will be a subset of  $\mathbb{R}^n$ .

$$A = \begin{bmatrix} 1 & 1 & 2 & -1 \\ 3 & -2 & 1 & 2 \\ 5 & 3 & 3 & -2 \end{bmatrix} \quad b = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$S = \{x \in \mathbb{R}^4 \mid x = (-t, 4t, t, 5t)\}$$

$-t + 4t + 2t - 5t = 0$  so it satisfies 1st equation.

$$\frac{dx_1}{dt} = 5t^2 x_1 - 3e^t x_2 + 2.8 \sin t$$

$$\frac{dx_2}{dt} = 6x_1 - 4x_2 + 3t^4$$

$$= \begin{bmatrix} 5t^2 & -3e^t \\ 6 & -4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 2.8 \sin t \\ 3t^4 \end{bmatrix}$$

$$\frac{d\vec{x}(t)}{dt} = A(t)x(t) + b(t)$$

Try Ex 2.3.8 on your own.